

$$\sigma = F/A \quad \varepsilon = \frac{(l + \Delta l) - l}{l} = \frac{\Delta l}{l} \quad \Delta l = \alpha_T \cdot \Delta t \cdot l + \frac{F \cdot l}{E \cdot A} \quad E = \frac{\sigma}{\varepsilon} \quad \nu = \left| \frac{\varepsilon_p}{\varepsilon_u} \right|$$

$$[\sigma_{ij}] = \begin{bmatrix} \sigma_{xx} & \tau_{xy} & \tau_{xz} \\ \tau_{xy} & \sigma_{yy} & \tau_{yz} \\ \tau_{xz} & \tau_{yz} & \sigma_{zz} \end{bmatrix} \quad \rho_n = |\sigma_{ij}| \cdot \dot{n} \quad \begin{bmatrix} \rho_{nx} \\ \rho_{ny} \\ \rho_{nz} \end{bmatrix} = [\sigma_{ij}] \cdot \begin{bmatrix} \cos(x, n) \\ \cos(y, n) \\ \cos(z, n) \end{bmatrix} \quad \rho_n = \sqrt{\rho_{nx}^2 + \rho_{ny}^2 + \rho_{nz}^2} \quad \sigma_n = \rho_n \cdot \dot{n} \\ \tau_n = \sqrt{\rho_n^2 - \sigma_n^2}$$

$$\begin{bmatrix} \sigma_{xx} & \tau_{xy} & \tau_{xz} \\ \tau_{xy} & \sigma_{yy} & \tau_{yz} \\ \tau_{xz} & \tau_{yz} & \sigma_{zz} \end{bmatrix} = \begin{bmatrix} \sigma_x - \sigma_s & \tau_{xy} & \tau_{xz} \\ \tau_{xy} & \sigma_y - \sigma_s & \tau_{yz} \\ \tau_{xz} & \tau_{yz} & \sigma_z - \sigma_s \end{bmatrix} + \begin{bmatrix} \sigma_s & 0 & 0 \\ 0 & \sigma_s & 0 \\ 0 & 0 & \sigma_s \end{bmatrix} \quad \sigma_s = \frac{1}{3} \cdot (\sigma_x + \sigma_y + \sigma_z)$$

$$\sigma_{1,2} = \frac{1}{2} \cdot (\sigma_{xx} + \sigma_{yy}) \pm \frac{1}{2} \cdot \sqrt{(\sigma_{xx} - \sigma_{yy})^2 + 4 \cdot \tau_{xy}^2} \quad \operatorname{tg} \varphi_{oi} = \frac{\tau_{yx}}{\sigma_i - \sigma_{yy}} \quad |\varphi_{01}| + |\varphi_{02}| = 90^\circ \quad \operatorname{tg}(2 \cdot \varphi_o) = \frac{2 \cdot \tau_{xy}}{\sigma_{xx} - \sigma_{yy}}$$

$$\sigma_{xx} + \sigma_{yy} + \sigma_{zz} = \sigma_1 + \sigma_2 + \sigma_3 \quad \sigma_1 \geq \sigma_2 \geq \sigma_3 \quad \varphi_1 = \varphi_0 + \frac{\pi}{4}$$

$$\sigma_{nn} = \sigma_{xx} \cdot \cos^2 \varphi + \sigma_{yy} \cdot \sin^2 \varphi + \tau_{xy} \cdot \sin(2 \cdot \varphi) = \frac{1}{2} \cdot (\sigma_{xx} + \sigma_{yy}) + \frac{1}{2} \cdot (\sigma_{xx} - \sigma_{yy}) \cdot \cos(2 \cdot \varphi) + \tau_{xy} \cdot \sin(2 \cdot \varphi)$$

$$\tau_{nn} = \frac{1}{2} \cdot (\sigma_{yy} - \sigma_{xx}) \cdot \sin(2 \cdot \varphi) + \tau_{xy} \cdot \cos(2 \cdot \varphi)$$

$$\tau_{12} = \pm \frac{1}{2} \cdot \sqrt{(\sigma_{xx} - \sigma_{yy})^2 + 4 \cdot \tau_{xy}^2} = \pm 0.5 \cdot (\sigma_1 - \sigma_2) \quad \tau_{MAX} = 0.5 \cdot (\sigma_1 - \sigma_2) \quad \sigma(\varphi_1) = 0.5 \cdot (\sigma_1 + \sigma_2)$$

$$\sigma_{OKT} = \frac{1}{3} \cdot (\sigma_1 + \sigma_2 + \sigma_3) = \frac{1}{3} \cdot (\sigma_{xx} + \sigma_{yy} + \sigma_{zz})$$

$$\tau_{OKT} = \frac{1}{3} \cdot \sqrt{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2} \quad \rho_{OKT} = \sqrt{\sigma_{OKT}^2 + \tau_{OKT}^2}$$

$$\sigma_{xx} = \frac{E}{(1+\nu) \cdot (1-2 \cdot \nu)} \cdot [(1-\nu) \cdot \varepsilon_{xx} + \nu \cdot (\varepsilon_{yy} + \varepsilon_{zz})]$$

$$\begin{bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{zz} \end{bmatrix} = \frac{E}{1-\nu^2} \cdot \begin{bmatrix} \varepsilon_{xx} + \nu \cdot \varepsilon_{yy} \\ \varepsilon_{yy} + \nu \cdot \varepsilon_{xx} \\ \varepsilon_{zz} + \nu \cdot \varepsilon_{xx} \end{bmatrix}$$

$$\varepsilon_{nn} = \varepsilon_{xx} \cdot \cos^2 \varphi + \varepsilon_{yy} \cdot \sin^2 \varphi + \varepsilon_{xy} \cdot \sin(2 \cdot \varphi)$$

$$\varepsilon_{xy} = \frac{\tau_{xy}}{2 \cdot G} = \frac{1+\nu}{E} \cdot \tau_{xy} = \frac{\gamma_{xy}}{2} \quad \varepsilon_{\begin{matrix} xy \\ yz \\ zx \end{matrix}} = \frac{1}{2 \cdot G} \cdot \tau_{\begin{matrix} xy \\ yz \\ zx \end{matrix}}$$

$$\varepsilon_d = (\varepsilon_x \cdot \cos^2 \alpha + \varepsilon_y \cdot \cos^2 \beta + \varepsilon_z \cdot \cos^2 \gamma) \quad G = \frac{E}{2 \cdot (1+\nu)}$$

$$\varepsilon_V = (\varepsilon_1 + \varepsilon_2 + \varepsilon_3) = \frac{1}{E} \cdot (1-2 \cdot \nu) \cdot (\sigma_1 + \sigma_2 + \sigma_3) + (3 \cdot \alpha_T \cdot \Delta t) = (\varepsilon_x + \varepsilon_y + \varepsilon_z) = \Delta V/V$$

ZAKOVICE $F_H = \frac{H}{n} \quad F_V = \frac{F}{n} \quad F_{ni} = \frac{M}{\sum \rho_i^2} \cdot \rho_i \quad R = \sqrt{F_x^2 + F_y^2} \quad \tau = \frac{R}{x \cdot \frac{d^2 \cdot \Pi}{4}} \leq \tau_{DOP} \quad \sigma = \frac{R}{d \cdot t} \leq \sigma_{DOP}$

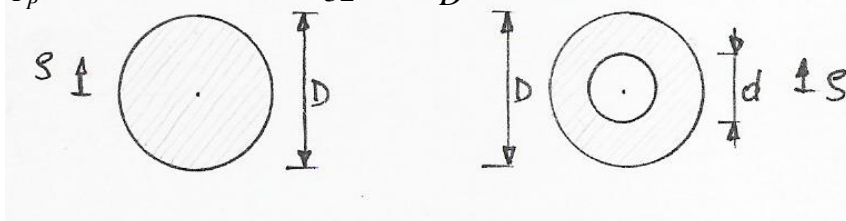
n = BROJ ZAKOVICA

X = REZNOST ZAKOVICA

ZAVAR $\sigma = \frac{F}{b \cdot t} \quad \tau = \frac{F}{x \cdot a \cdot l} \leq \tau_{DOP} \quad a = 0.7 \cdot t \quad x = \text{BROJ VAROVA}$

TORZIJA $\tau = \frac{M_t}{I_p} \cdot \rho \quad \tau_{MAX} = \frac{M_t}{I_p} \cdot r = \frac{M_t}{W_p} \quad I_p = \frac{\Pi \cdot D^4}{32} \quad W_p = \frac{I_p}{r} \quad W_p = \frac{\Pi \cdot D^3}{16}$

$$\varphi = \frac{M_t}{G \cdot I_p} \cdot l \quad I_p = \frac{\Pi \cdot D^4}{32} \left(1 - \frac{d^4}{D^4}\right) \quad W_p = \frac{\Pi \cdot D^3}{16} \cdot \left(1 - \frac{d^4}{D^4}\right)$$



POSUDE TANKIH STIJENKI $\varepsilon_1 = \frac{1}{E} \cdot (\sigma_1 - \nu \cdot \sigma_2) \quad \frac{\sigma_1}{\rho_1} + \frac{\sigma_2}{\rho_2} = \frac{p}{h}$

KUGLA $\sigma_1 = \sigma_2 = \sigma \quad \rho_1 = \rho_2 = r \quad \sigma = \frac{p \cdot r}{2 \cdot h} \quad \varepsilon = \frac{\Delta r}{r} = \frac{1-\nu}{E} \cdot \sigma \quad \Delta r = \frac{1-\nu}{E} \cdot \frac{p \cdot r^2}{2 \cdot h}$

CILINDRIČNA POSODA $\rho_1 = r \quad \rho_2 = \infty \quad \sigma_1 = \frac{p \cdot r}{h} \quad \sigma_2 = \frac{p \cdot r}{2 \cdot h} \quad \varepsilon_1 = \frac{1-0.5 \cdot \nu}{E} \cdot \sigma_1 = \frac{\Delta r}{r}$

PRSTEN $\rho_1 = r \quad \rho_2 = \infty \quad \sigma_1 = \sigma \quad \sigma_2 = 0 \quad \sigma = \frac{p \cdot r}{h} \quad \varepsilon = \frac{\Delta r}{r} = \frac{\Delta D}{D} \quad \Delta r = \frac{p \cdot r^2}{E \cdot h}$

GEOMETRIJSKE KARAKTERISTIKE PRAVOKUTNIKA

$I_z = \frac{b \cdot h^3}{12} \quad I_y = \frac{h \cdot b^3}{12} \quad W_z = \frac{bh^2}{6} \quad W_y = \frac{hb^2}{6} \quad i_z = \sqrt{\frac{I_z}{A}} \quad i_y = \sqrt{\frac{I_y}{A}}$

STEINEROV TEOREM $I_y = I_{y,VL} + d^2 \cdot A$ (d - UDALJENOST OD OSI y DO TEŽIŠTA A)

GLAVNE OSI PRESJEKA

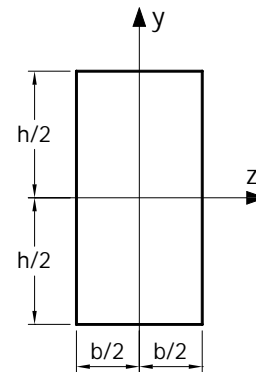
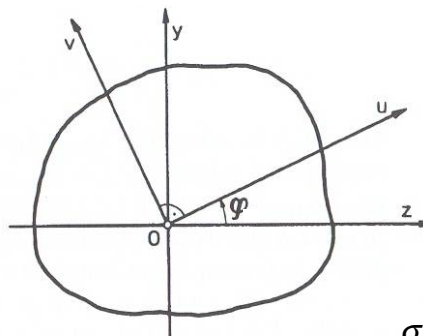
$I_{1,2} = \frac{1}{2} \cdot (I_z + I_y) \pm \frac{1}{2} \cdot \sqrt{(I_z - I_y)^2 + 4 \cdot I_{zy}^2}$

$I_z > I_y \rightarrow I_U = I_{MAX} \rightarrow I_V = I_{MIN}$

$I_z < I_y \rightarrow I_U = I_{MIN} \rightarrow I_V = I_{MAX}$

$\text{tg}(2 \cdot \varphi) = -2 \cdot \frac{I_{zy}}{I_z - I_y}$

$I_1 + I_2 = I_z + I_y$



SAVIJANJE $\sigma_{xxMAX} = \frac{M_{MAX}}{I_y} \cdot z_{MAX} = \frac{M}{W_y} \quad \tau_{xz} = \frac{T_z \cdot S_y}{I_y \cdot b}$

$\sigma_{xx} = \frac{M}{I_y} \cdot z \pm \frac{N}{A} < \sigma_{DOP}$

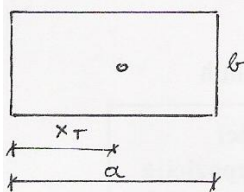
KOSO SAVIJANJE $M_y = M \cdot \cos \alpha \quad M_z = M \cdot \sin \alpha \quad \sigma_{xx} = \pm \left(\frac{M_y}{I_y} \cdot z + \frac{M_z}{I_z} \cdot y \right) \leq \sigma_{DOP} \quad \text{tg} \varphi = -\frac{I_y}{I_z} \cdot \text{tg} \alpha$

GRAFOANALITIČKI

$\bar{q} = \frac{M}{E \cdot I}$

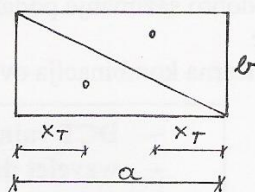
$\varphi = \frac{\bar{T}}{E \cdot I}$

$w = \frac{\bar{M}}{E \cdot I}$



$P = a \cdot b$

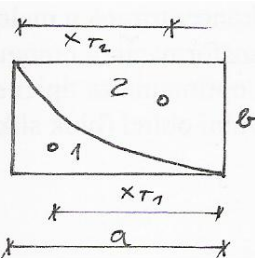
$x_T = 0.5 \cdot a$



$P = 0.5 \cdot a \cdot b$

$x_T = \frac{1}{3} \cdot a$

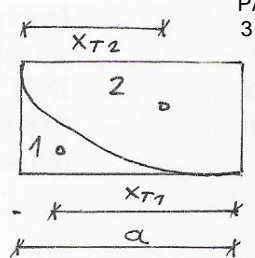
PARABOLA 2 STUPNJA



$P_2 = \frac{2}{3} \cdot a \cdot b \quad P_1 = \frac{1}{3} \cdot a \cdot b$

$x_{T2} = \frac{5}{8} \cdot a \quad x_{T1} = \frac{3}{4} \cdot a$

PARABOLA 3 STUPNJA



$P_2 = \frac{3}{4} \cdot a \cdot b \quad P_1 = \frac{1}{4} \cdot a \cdot b$

$x_{T2} = \frac{3}{5} \cdot a \quad x_{T1} = \frac{4}{5} \cdot a$

ANALITIČKI $-q(x) = \frac{dT(x)}{dx} = \frac{d^2M(x)}{dx^2} \quad \frac{-M(x)}{EI} = \frac{d\varphi}{dx} \quad \frac{-M(x)}{EI} = \frac{d^2w}{dx^2} \quad (x - a_i) > 0$

CENTAR TORZIJE

$M_x = \int_A (\tau_{xz} \cdot y - \tau_{xy} \cdot z) dA \quad T_z \cdot e = M_x = \int_A (\tau_{xz} \cdot y - \tau_{xy} \cdot z) dA$

$\tau = \frac{T \cdot S}{I \cdot b}$

$\tau_{xy} = \frac{T}{I_y \cdot t} \cdot (t \cdot S \cdot 0.5 \cdot h)$

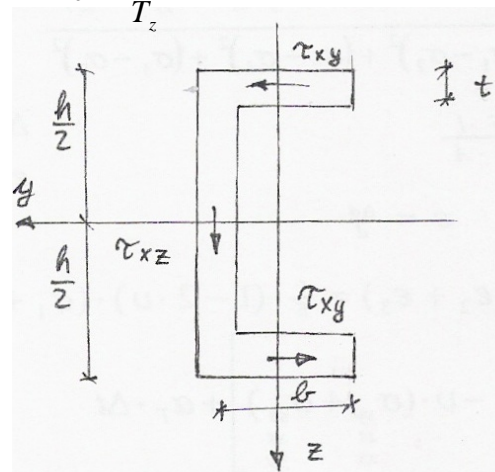
$\tau_{xz} = \frac{T}{I_y \cdot t} \cdot [0.5 \cdot t \cdot b \cdot h + 0.5 \cdot t \cdot (0.25 \cdot h^2 - z^2)]$

$T_1 = \int_0^b \tau_{xy} \cdot t \, ds = 0.5 \cdot \tau_{xy} \cdot b \cdot t$

$T_2 = \int_{-\frac{h}{2}}^{\frac{h}{2}} \tau_{xz} \cdot t \, dz$

$T_z \cdot e = T_1 \cdot h$

$e = \frac{M_x}{T_z}$



MOŽDANICI $\sigma_x = \frac{M_{MAX}}{f \cdot W_{yn}}$ $f = \text{PODATLJIVOST SPOJA}$ $R_x = \frac{T_{Z(MAX)} \cdot S_{yb}}{I_{yb}} \cdot l$ $R_x = \text{HORIZONTALNA POSMIČNA SILA NA DUŽINI l}$

$\sigma_o = \frac{R_x}{c \cdot b} \leq \sigma_{DOP}$ $\tau = \frac{R_x}{a \cdot b} \leq \tau_{DOP}$ $\tau = \frac{R_x}{b \cdot (l-a)} \leq \tau_{DOP}$

TEORIJE ČVRSTOĆE $\sigma_E < \sigma_{DOP}$ $\sigma_D = \frac{\sigma_E}{K}$ $\sigma_E = \frac{M_E}{W_y} < \sigma_D$

1. NAJVEĆA NORMALNA

a) TROOSNO $\sigma_E = |\sigma_1| \leq \sigma_{DOP}$

b) SAVIJANJE $\sigma_E = 0.5 \cdot \sigma + 0.5 \cdot \sqrt{\sigma^2 + 4 \cdot \tau^2}$

c) SAVIJANJE I TORZIJA $M_E = 0.5 \cdot (M_S + \sqrt{M_S^2 + M_T^2})$

2. NORMALNE DEFORMACIJE

a) $\sigma_E = \sigma_1 - \nu \cdot (\sigma_2 + \sigma_3) \leq \sigma_{DOP}$

b) $\sigma_E = 0.5 \cdot (1 - \nu) \cdot \sigma + 0.5 \cdot (1 + \nu) \cdot \sqrt{\sigma^2 + 4 \cdot \tau^2}$

c) $M_E = 0.5 \cdot (1 - \nu) \cdot M_S + 0.5 \cdot (1 + \nu) \cdot \sqrt{M_S^2 + M_T^2}$

3. POSMIČNA NAPREZANJA

a) $\sigma_E = \sigma_1 - \sigma_3 \leq \sigma_{DOP}$

b) $\sigma_E = \sqrt{\sigma^2 + 4 \cdot \tau^2}$

c) $M_E = \sqrt{M_S^2 + M_T^2}$

4. POTENCIJALNA ENERGIJA DEFORMACIJA

a) $\sigma_E = \sqrt{\sigma_1^2 + \sigma_2^2 + \sigma_3^2 - 2 \cdot \nu \cdot (\sigma_1 \sigma_2 + \sigma_2 \sigma_3 + \sigma_3 \sigma_1)} \leq \sigma_{DOP}$

b) $\sigma_E = \sqrt{\sigma^2 + 2 \cdot (1 + \nu) \cdot \tau^2}$

c) $M_E = \sqrt{M_S^2 + 0.5 \cdot (1 + \nu) \cdot M_T^2}$

5. POTENCIJALNA ENERGIJA PROMJENE OBLIKA

a) $\sigma_E = \sqrt{0.5 \cdot [(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2]} \leq \sigma_{DOP}$

b) $\sigma_E = \sqrt{\sigma^2 + 3 \cdot \tau^2}$

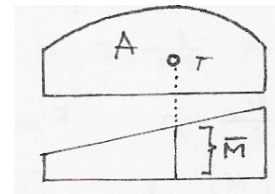
c) $M_E = \sqrt{M_S^2 + 0.75 \cdot M_T^2}$

ENERGIJA $U = \int_0^l \frac{N^2 dx}{2 \cdot E \cdot A} + \int_0^l k_y \cdot \frac{T_y^2 dx}{2 \cdot G \cdot A} + \int_0^l k_z \cdot \frac{T_z^2 dx}{2 \cdot G \cdot A} + \int_0^l \frac{M_T^2 dx}{2 \cdot G \cdot I_T} + \int_0^l \frac{M_y^2 dx}{2 \cdot E \cdot I_y} + \int_0^l \frac{M_z^2 dx}{2 \cdot E \cdot I_z}$

$\delta = \frac{\partial U}{\partial F}$ $\varphi = \frac{\partial U}{\partial M}$ $F = \frac{\partial U}{\partial \delta}$

METODA JEDINIČNOG OPTEREČENJA $\delta_k = \int_0^l \frac{N \cdot \bar{N}_k dx}{E \cdot A} + \dots + \int_0^l \frac{M_y \cdot \bar{M}_{yk} dx}{E \cdot I_y}$

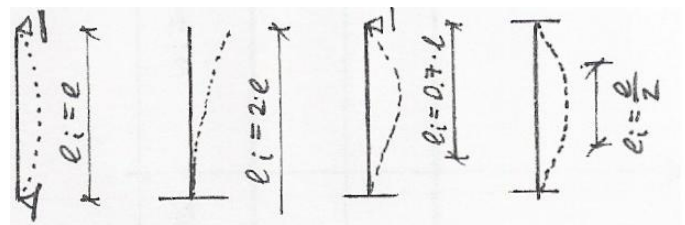
$\delta_k = \sum_{i=1}^n \frac{A_{Ni} \cdot \bar{N}_{ki}}{(E \cdot A)_i} + \dots + \sum_{i=1}^n \frac{A_{Mi} \cdot \bar{M}_{ki}}{(E \cdot I)_i}$



IZVIJANJE

$F_{KR} = \frac{\Pi^2 \cdot EI_{MIN}}{l_i^2}$ $\sigma_{KR} = \frac{F_{KR}}{A} = \frac{\Pi^2 \cdot EI_{MIN}}{A \cdot l_i^2}$ $i_{MIN} = \sqrt{\frac{I_{MIN}}{A}}$ $\lambda = \frac{l_i}{i_{MIN}}$ $\lambda^2 = \frac{l_i^2}{i_{MIN}^2} = \frac{A \cdot l_i^2}{I_{MIN}}$

$\sigma_{KR} = \frac{\Pi^2 \cdot E}{\lambda^2} \leq \sigma_p$ $\lambda_p = \sqrt{\frac{\Pi^2 \cdot E}{\sigma_p}}$ $\sigma_{DOP} = \frac{\sigma_{KR}}{k}$





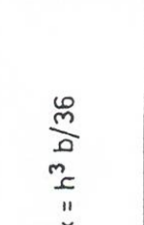

EULEROVA HIPERBOLA $\sigma_{KR} = \frac{\Pi^2 \cdot E}{\lambda^2}$

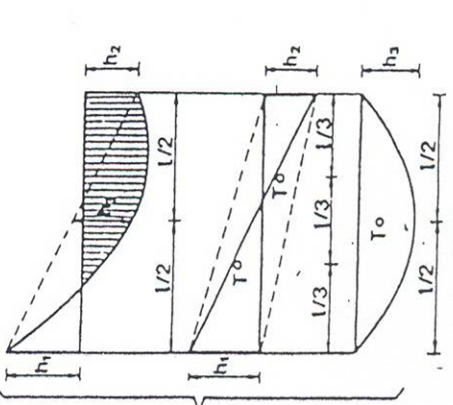
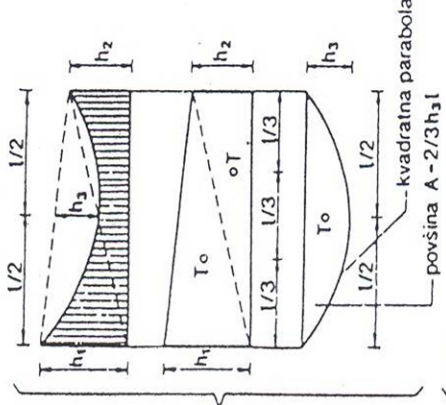
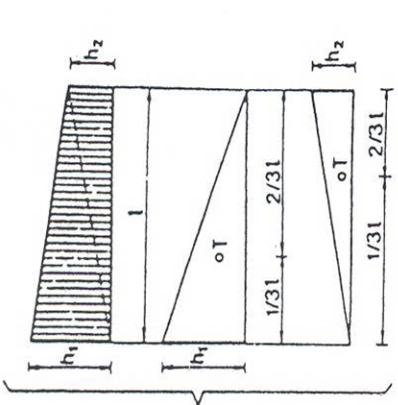
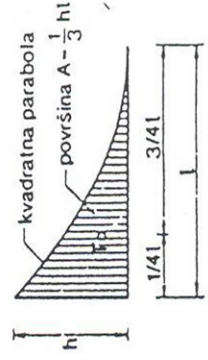
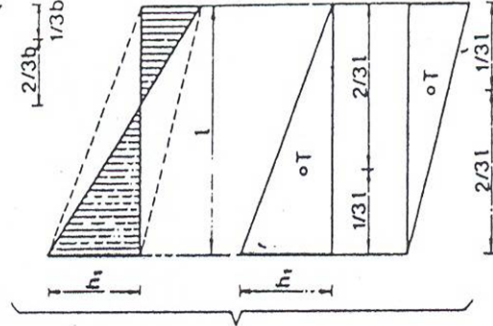
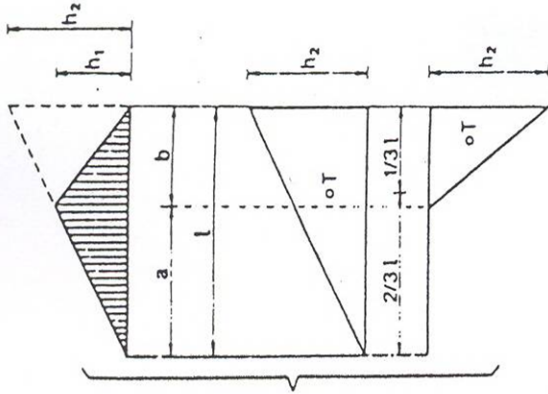
TETMAYEROV PRAVAC $\sigma_{KR} = a - b \cdot \lambda$

TEORIJA PLASTIČNOSTI $W_{pl} = S_T + S_V$ $S_T = A_T \cdot h_T$ $S_V = A_V \cdot h_V$ $A_T = A_V$

$W_V + W_U = 0$ $W_i = F \cdot \delta + M \cdot \varphi$

$W_{pl} = \frac{b \cdot h^2}{4}$ $M_{pl} = \sigma_T \cdot W_{pl}$

 <p>$e = \frac{2}{3} h$</p>	$I_x = h^3 b / 36$	$W_x = h^2 b / 24$
	$I_x = I_y = 0.5413 a^4$	$W_x = 0.625 a^3$ $W_y = 0.5413 a^3$
	$I_x = \frac{h^3}{36} \frac{a^2 + 4ab + b^2}{a + b}$	$W_x = \frac{h^2}{12} \frac{a^2 + 4ab + b^2}{2a + b}$
	$I_x = I_y = \frac{\pi D^4}{64}$	$W_x = W_y = \frac{\pi D^3}{32}$
	<p>a) $I_x = I_y = \frac{\pi}{64} (D^4 - d^4)$</p>	$W_x = W_y = \frac{\pi}{32} \cdot \frac{(D^4 - d^4)}{D}$
	<p>b) za malu debljinu stijenke t: $I_x = I_y \approx \pi R_{sr}^3 t$ $R_{sr} = \frac{(D+d)}{2}$</p>	$W_x = W_y \approx R_{sr}^2 t$
	$I_x = \pi a^3 b / 4$ $I_y = \pi b^3 a / 4$	$W_x = \pi a^2 b / 4$ $W_y = \pi b^2 a / 4$
	$I_x \approx 0,007 D^4$	$W_x \approx 0,024 D^3$
	$I_x = \frac{b_2 h_2^3 - b_1 h_1^3}{12}$	$W_x = \frac{b_2 h_2^3 - b_1 h_1^3}{6 h_2}$



kvadratna parabola
površina $A = 2/3 h_2 l$

kvadratna parabola
površina $A = \frac{1}{3} h_1 l$